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Pathspace Representation of Affine Processes $\[\]$ Introduction

Option Pricing The problem:

given

- $(X_t^x)_{t \in [0,T]}$ stock process
- *H* payoff function, possibly depending on the whole path up to time T

find
$$\mathbb{E}^{X} \Big[H(X_t, t \in [0, T]) \Big].$$

Example

$$\begin{aligned} H: \mathcal{D}(\mathbb{R}_{\geq 0}; D) &\to \mathbb{R}_{\geq 0} \\ X^{x} &\mapsto H(X^{x}) := \max\left(X_{T}^{x} - K, 0\right) \\ X^{x} &\mapsto H(X^{x}) := \max\left(\int_{0}^{T} X_{t}^{x} dt - K, 0\right) \end{aligned}$$

Introduction



Approximation of trajectories by MC methods

step 1 Fix a uniform partition in
$$[0, T]$$

 $\{t_0 = 0, ..., t_k = kh, ..., t_N = T\}, \quad h = \frac{T}{N}.$
step 2 Find a piecewise constant approximating process
 $(\widehat{X}_{t_k})_{k=0,...,N}$ such that
 $- \widehat{X}_{t_0} = x,$
 $- \widehat{X}$ is a weak ν -order approximation of X^x .

Definition

For every $f \in C^{\infty}$ with compact support there exists a K > 0 such that

$$\left|\mathbb{E}^{\mathsf{X}}\left[f(X_{\mathcal{T}})\right] - \mathbb{E}^{\mathsf{X}}\left[f(\widehat{X}_{t_{\mathsf{N}}})\right]\right| \leq \mathsf{K}h^{\nu}.$$

Find the approximating sequence

Original process: X^x a time-homogeneous Markov process with state space D and associated semigroup

$$P_t f(x) := \mathbb{E}^x \Big[f(X_t) \Big], \quad f \in \mathcal{M},$$

 \mathcal{M} space of measurable functions where $\mathbb{E}^{x} \left[f(X_{t}) \right]$ is well defined.

Approximated process: \hat{X}^x with transition semigroup Q_h which is bounded and

$$\lim_{N\to\infty} (Q_h)^N f = P_T f.$$

If \widehat{X} is a good approximation of X we need

- 1. $(Q_h)^k$ to be close to P_{t_k} ,
- 2. short time asymptotic

 $|Q_h P_s f - P_h P_s f| \le K \rho(x) h^{\nu+1}$, for all $f \in \mathcal{M}$, $h, s \in [0, T]$,

3. $P_t \mathcal{M} \subseteq \mathcal{M}$ to do the iteration.

From single step to multi-step

$$(Q_h)^N - P_T f = \sum_{k=1}^{N-1} (Q_h)^{N-k} (Q_h - P_h) P_{t_k} f$$

Follow the lines of ODE approximation

If $f \in C^2$ with bounded derivative, from Dynkin formula

$$\mathbb{E}^{\mathsf{x}}\left[f(X_{h})\right] = f(x) + h \int_{0}^{1} \mathbb{E}^{\mathsf{x}}\left[\mathcal{A}f(X_{sh})\right] ds.$$

Iterating...

$$\mathbb{E}^{x}\left[f(X_{h})\right] = f(x) + \sum_{k=1}^{\nu} \frac{h^{k}}{k!} \mathcal{A}^{k} f(x)$$
$$+ \frac{h^{\nu+1}}{\nu!} \int_{0}^{1} (1-s)^{\nu} \mathbb{E}^{x}\left[\mathcal{A}^{\nu+1} f(X_{sh})\right] ds$$

How far can we go with the space of test function \mathcal{M} ?

The choice of test functions

Take $\mathcal{M} = C_{\text{pol}}^{\infty}$ (see [Jacod et al., 2005], [Alfonsi, 2010])

Definition (The function space C_{pol}^k)

- A function $f \in C_{\text{pol}}^k$ if
 - ▶ $f \in C^k$
 - for all α multi-index with |α| ≤ k, there exist constants C_α and e_α such that

$$|\partial^{\alpha} f(x)| \leq C_{\alpha}(1+|x|^{e_{\alpha}}), \quad \text{ for all } x \in D.$$

Theorem (Theorem 1.9 in [Alfonsi, 2010])

Under the assumptions

- 1. (Uniform bounded moments)
- 2. $(\nu order asymptotic of the local error)$
- 3. (Regularity Kolmogorov PIDE) f is a function such that $u(t,x) = \mathbb{E}^{x} [f(X_{T-t})]$ is the solution of the PIDE

$$\partial_t u(t,x) + \mathcal{A}u(t,x) = 0$$
 with $u(t,x) \in C_{pol}^k$

Then \widehat{X}^{x} is a weak ν -order scheme for X^{x} .

Two types of error



Figure : Geometrical interpretation of the local truncation error and the true error. The picture in taken from [Quarteroni et al., 2010]

Pathspace Representation of Affine Processes $\[\]$ Introduction

Problem 1

Find Q_h such that

$$\lim_{N\to\infty} (Q_{\frac{t}{N}})^N f = P_t f.$$

High dimensional state space

 \hookrightarrow High order numerical schemes

Domain constrains

 \hookrightarrow Geometry preserving schemes

Problem 2

Is the stability condition satisfied?

Feynman-Kac representation

If u is a classical solution of

$$\partial_t u(t,x) + \mathcal{A}u(t,x) = 0$$

and its derivatives are bounded by a polynomial function uniformly in t, then it has the probabilistic representation

$$u(t,x) = \mathbb{E}^{x} \Big[f(X_{T-t}) \Big].$$

 \hookrightarrow Is *u* smooth enough?

Regularity of the solution of the Kolmogorov PIDE

- Regularity of the Kolmogorov equation in time is easier to handle(Dynkin formula) than regularity in space.
- Idea: Switch time and space, what do you get?

Example: One dimensional case in $\mathbb{R}_{>0}$

 $(X_t^x)_{t\geq 0}$

Regularity of the solution of the Kolmogorov PIDE

- Regularity of the Kolmogorov equation in time is easier to handle(Dynkin formula) than regularity in space.
- Idea: Switch time and space , what do you get?

Example: One dimensional case in $\mathbb{R}_{>0}$

 $(X_t^{\mathbf{x}})_{\mathbf{x}\geq 0}$

Pathspace representation

$$X_t^x := x + 2 \int_0^t \sqrt{X_s} dW_s$$

$$X_t^x \stackrel{d}{=} L_x^t$$

$$L_x^t := 2t \sum_{k=1}^{N_{x/(2t)}} e_k$$

Pathspace representation

$$X_t^x := x + 2 \int_0^t \sqrt{X_s} dW_s$$

$$X_t^x \stackrel{d}{=} L^t_x$$

$$L_x^t := 2t \sum_{k=1}^{N_{x/(2t)}} e_k$$

Pathspace representation

$$X_{t}^{*} := \mathbf{x} + 2 \int_{0}^{t} \sqrt{X_{s}} dW_{s}$$
$$X_{t}^{*} := 2t \sum_{k=1}^{N_{x/(2t)}} \mathfrak{e}_{k}$$

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Structure of the talk

Affine processes

From Affine Processes to Lévy Processes and back

Path approximation by Time-Space transformations

Regularity solution Kolmogorov PIDE

Conclusions

Outline

Affine processes

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Affine processes

Affine processes on the canonical state space

An *affine processes* on the canonical state space $D = \mathbb{R}^m_{\geq 0} \times \mathbb{R}^n$ is a time homogeneous Markov process

$$X = (\Omega, (\mathcal{F}_t)_{t \ge 0}, (p_t)_{t \ge 0}, (X_t)_{t \ge 0}, (\mathbb{P}^x)_{x \in D_{\Delta}})$$

satisfying the following properties:

- ► (stochastic continuity) for every $t \ge 0$ and $x \in D$, $\lim_{s \to t} p_s(x, \cdot) = p_t(x, \cdot)$ weakly,
- (affine property) there exist functions $\phi : \mathbb{R}_{\geq 0} \times \mathcal{U} \to \mathbb{C}$ and $\Psi : \mathbb{R}_{\geq 0} \times \mathcal{U} \to \mathbb{C}^d$ such that

$$\mathbb{E}^{x}\left[e^{\langle u,X_{t}\rangle}\right] = \int_{D} e^{\langle u,\xi\rangle} p_{t}(x,d\xi) = e^{\phi(t,u) + \langle \Psi(t,u),x\rangle}$$

for all $x \in D$ and $(t, u) \in \mathbb{R}_{\geq 0} \times \mathcal{U}$, with

 $\mathcal{U} = \left\{ u \in \mathbb{C}^d \mid e^{\langle u, x \rangle} \text{ is a bounded function on } D \right\}.$ (1)

From affine processes to linear processes

Let AP(D) be the space of affine processes with state space D. Define the map

$$\infty: AP(\mathbb{R}^m_{\geq 0} \times \mathbb{R}^n) \to AP(\mathbb{R}^{m+1}_{\geq 0} \times \mathbb{R}^n)$$
$$X \mapsto X^{\infty}$$

Input: X with
$$\mathbb{E}^{x}\left[e^{\langle u, X_{t}\rangle}\right] = e^{\phi(t,u) + \langle x, \Psi(t,u)\rangle}$$

Output: X ^{∞} with $\mathbb{E}^{(1,x)}\left[e^{\langle u, X_{t}^{\infty}\rangle}\right] = e^{\langle (1,x), \Psi^{\infty}(t,u)\rangle}$ where

$$\Psi^{\infty}(t, u_0, u_1, \ldots, u_d) := \begin{pmatrix} \phi(t, u_1, \ldots, u_d) + u_0 \\ \Psi(t, u_1, \ldots, u_d) \end{pmatrix}$$

Affine processes

Linear structure

There exists a function $\Psi:\mathbb{R}_{>0}\times\mathcal{U}\rightarrow\mathbb{C}^d$ such that

$$\mathbb{E}^{x}\left[e^{\langle u, X_{t}\rangle}\right] = \int_{D} e^{\langle u, \xi\rangle} p_{t}(x, d\xi) = e^{\langle \Psi(t, u), x\rangle}$$

Affine processes

Generalized Riccati equations

On the set $Q = \mathbb{R}_{\geq 0} \times U$, the function Ψ satisfies the following system of generalized Riccati equations:

Generalized Riccati equations

$$\partial_t \Psi(t, u) = \mathbf{R}(\Psi(t, u)), \quad \Psi(0, u) = u$$

where for each k = 1, ..., d the function \mathbf{R}_k has the following Lévy-Khintchine form

$$\begin{aligned} \mathbf{R}_{k}(u) &= \langle \beta_{k}, u \rangle + \frac{1}{2} \langle u, \alpha_{k} u \rangle - \gamma_{k} \\ &+ \int_{D \setminus \{0\}} \left(e^{\langle u, \xi \rangle} - 1 - \langle \pi_{J \cup \{k\}} u, \pi_{J \cup \{k\}} h(\xi) \rangle \right) M_{k}(d\xi). \end{aligned}$$



Infinite divisibility in D

Let $\mathcal C$ the *convex cone* of continuous function $\eta:\mathcal U\to\mathbb C_+$ of type

$$\eta(u) = \langle \mathsf{b}, u \rangle + \frac{1}{2} \langle \pi_J u, \sigma \pi_J u \rangle + \int_{D \setminus \{0\}} \left(e^{\langle u, \xi \rangle} - 1 - \langle \pi_J u, \pi_J h(\xi) \rangle \right) \nu(d\xi). \qquad (*)$$

Definition

A distribution λ on D_{Δ} is *infinitely divisible* if and only if its Laplace transform takes the form $e^{\eta(u)-c}$, where η has the form (*) and $c = \log \lambda(D)$.

 $p_t(x, \cdot)$ is infinitely divisible in D!



Affine processes

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From affine processes to Lévy processes

Let $(\mathcal{D}(\mathbb{R}_{\geq 0}; D_{\Delta}), (\mathcal{F}_t)_{t\geq 0}, (p_t)_{t\geq 0}, (X_t)_{t\geq 0}, (\mathbb{P}^x)_{x\in D_{\Delta}})$ be a linear process on the canonical state space $D = \mathbb{R}^m_{>0} \times \mathbb{R}^n$.

Proposition

For each fixed t > 0 and $x \in D \setminus \{0, \Delta\}$, there exists process $(L_{sx}^t)_{s \in [0,1]}$ such that:

- 1. $L_0^t = 0$,
- 2. for every $0 \le s_1 \le s_2 \le 1$, the increment $L_{s_2x}^t L_{s_1x}^t$ is independent of the family $(L_{s_x}^t)_{s \in [0,s_1]}$ and it distributed as $X_t^{(s_2-s_1)x}$.

Moreover for any fixed $t \ge 0$, and $x \in D$ there exists a unique modification \tilde{L}^t of L^t which is a Lévy process with càdlàg paths.

From Affine Processes to Lévy Processes and back

The proof

Apply Kolmogorov's existence Theorem with the convolution semigroup $(p_t(sx, \cdot))_{s \ge 0}$.

 $\label{eq:chapman-Kolmogorov's equations} \rightarrow \text{Semigroup property in time}$

$$p_{s+t}(x,\cdot) = p_s \cdot p_t(x,\cdot) := \int p_t(x,dy) p_s(y,\cdot),$$

Linearity \rightarrow Convolution property in space $p_t(x + y, \cdot) = p_t(x, \cdot) * p_t(y, \cdot).$

From Affine Processes to Lévy Processes and back

Let t run

Remark: Here *t* appears here as a parameter of $(L_{sx}^t)_{s \in [0,1]}$.

ldea: Let t evolve and consider the above construction on the path space.

Result: Construct a path valued process $(L_{sx})_{s \in [0,1]}$ which starts in zero and it reaches $(X_t^x)_{t \ge 0}$ at time 1. here

From Affine Processes to Lévy Processes and back

Make things rigorous

Theorem

There exists a process $(L_{sx})_{s\geq 0}$ taking values in $\mathcal{D}(\mathbb{R}_{\geq 0}; D_{\Delta})$ such that

- 1. it has stationary and independent increments,
- 2. it is stochastically continuous,

3. it holds

$$\mathbb{E}^{\mathsf{X}}\left[e^{\langle u, \mathsf{X}_t \rangle}\right] = e^{\langle \mathsf{X}, \Psi(t, u) \rangle} = \mathbb{E}\left[e^{\langle u, \mathsf{ev}_t(\mathsf{L}_{\mathsf{s}\mathsf{X}}) \rangle}\right]_{|_{\mathsf{s}=1}}$$

Proof: Apply Kolmogorov's existence Theorem with the convolution semigroup $\wp_s(x, \cdot) := \mathbb{P}^{sx}, s \ge 0.$



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A guiding principle



Lévy-Kintchine decomposition of an affine process

step 1 Solve $\Psi(t, u) = u + \int_0^t \mathbf{R}(\Psi(s, u)) ds$, $u \in \mathcal{U}$. step 2 Do Lévy-Khintchine decomposition of $\Psi(t, u)$.

Approximation Riccati equations

1. Fix
$$N > 0$$
, $T > 0$ and a partition $\{t_0 = 0, t_1 = h, ..., t_N = T\}$ with $h = \frac{T}{N}$.

2. Let y_n be the approximation of $\Psi(t_n, u)$.

Example: Forward Euler's method

For small h,

$$\mathbb{E}^{x}\left[e^{\langle u, X_{h}\rangle}\right] = e^{\langle x, u\rangle + h\langle x, \mathsf{R}(u)\rangle}, \quad u \in \mathcal{U}.$$

• X_t^x is infinitely divisible in $D = \mathbb{R}_{\geq 0}^m \times \mathbb{R}^n$ but $\langle x, \mathbf{R}(u) \rangle$ has the Lévy-Khintchine representation in \mathbb{R}^d ! (here)

 \rightsquigarrow Seek methods that preserve positivity of the semiflow.

Example 1: Feller diffusion +++ homographic ray

$$\mathbb{E}\left[e^{u\mathcal{L}_{x}^{t}}\right] = \exp\left(x\frac{u}{1-\frac{ut}{2}}\right), \quad \mathcal{R}e(u) < \frac{2}{t},$$

Affine process on $\mathbb{R}_{\geq 0}$ with functional characteristic $\mathbf{R}(u) = \frac{1}{2}u^2$.

Exact approximation

$$\begin{array}{llll} \widehat{X}_0^x &=& x,\\ \widehat{X}_{t_{k+1}}^x &=& \left(\mathcal{L}_{sx}^h\right)_{s=1,x=\widehat{X}_{t_k}^x}, \ k\geq 0 \end{array}$$

where $\mathcal{L}_{\cdot x}^{t}$ is a subordinator with $\nu(t, x, d\xi) := \frac{4x}{t^2} e^{-\frac{2\xi}{t}} d\xi.$



Example 2: Neveu Branching ++++ stable ray

$$\mathbb{E}\left[e^{u\mathcal{J}_{x}^{t}}\right] = \exp\left(-x(-u)^{e^{-t}}\right)$$

Affine process on $\mathbb{R}_{\geq 0}$ with functional characteristic $\mathbf{R}(u) = -u \log(-u)$.

Exact approximation

$$\begin{aligned} \widehat{X}_0^x &= x\\ \widehat{X}_{t_{k+1}}^x &= \left(\mathcal{J}_{sx}^h\right)_{s=1,x=\widehat{X}_{t_k}^x}, \ k \geq 0. \end{aligned}$$

where $\mathcal{J}_{\cdot x}^{t}$ is a subordinator with $\nu(t, x, d\xi) := \frac{xe^{-t}}{\Gamma(1-e^{-t})}\xi^{-1-e^{-t}}d\xi.$



Path approximation by Time-Space transformations

CIR with jumps

The Model:

$$dZ_{t}^{z} = cZ_{t}^{z}dt + \sqrt{Z_{t}^{z}}dW_{t} + \int_{|\xi|>1} \xi N(ds, d\xi) + \int_{|\xi|\leq 1} \xi (N(dt, d\xi) - \frac{d\xi}{\xi^{2}}Z_{t}^{z}dt) R^{C+J}(u) = \boxed{cu + \frac{1}{2}u^{2}} + \boxed{\int_{0}^{\infty} (e^{u\xi} - 1 - u\xi \mathbb{1}_{|\xi|\leq 1}) \frac{d\xi}{\xi^{2}}}$$

Idea: Split the vector field

$$R^{C+J}(u) = R^{C}(u) + R^{J}(u)$$

$$\downarrow \qquad \qquad \downarrow$$
Feller Diffusion Neveu CSBP

Geometry preserving schemes

1. Let
$$\widehat{\Psi}(h, u) := \Psi^J(h, \Psi^C(h, u)).$$

2. Define

$$y_0(u) = u$$

 $y_{n+1}(u) = \widehat{\Psi}(h, y_n(u)) \qquad n = 0, \dots, N-1.$

3. $\lim_{n\to\infty} y_N(u) =: \Psi^{C+J}(t, u)$ with

$$\Psi^{C+J}(t, u) = u + \int_0^t R^{C+J}(\Psi^{C+J}(s, u)) ds.$$

Remark: $P_T f = \lim_{N \to \infty} (Q_h f)^N$, $Q_h := P_h^C P_h^J$. Other examples: \square



Affine processes

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Set the notation

Consider

$$u(t,x) = \mathbb{E}^{x} \left[f(X_{T-t}) \right] \stackrel{\text{not.!}}{=} \mathbb{E} \left[f(L_{s}^{(T-t,x)}) \right]_{s=1}$$

Introduce

$$v^{(t,x)}(s,y) = \underbrace{\mathbb{E}^{y}\left[f(L_{(1-s)}^{(T-t,x)})\right]}_{\text{it evolves in time } s} = \mathbb{E}\left[f(L_{(1-s)}^{(T-t,x)}+y)\right].$$

Remark: Regularity in x for u(t, x) can be obtained by regularity in s of $v^{(t,x)}(s, y)$.

Regularity solution Kolmogorov PIDE

Change the perspective

General case: $(L_s^{(t,x)})_{s\geq 0}$ is a Lévy process with infinitesimal generator

$$\mathcal{L}^{(t,x)}f(y) = \frac{1}{2}\operatorname{Tr}(\sigma(t,x) \triangle f(y)) + \langle b(t,x), \nabla f(y) \rangle \\ + \int (f(y+\xi) - f(y) - \langle \xi, \nabla f(y) \rangle) \nu(t,x,d\xi).$$

Processes on $\mathbb{R}^{m}_{\geq 0}$: $(L_{s}^{(t,x)})_{s\geq 0}$ is a subordinator. Feller diffusion: $(L_{s}^{(t,x)})_{s\geq 0}$ is a compound Poisson process with Lévy measure

$$\nu(t, x, d\xi) = \frac{x}{(2t)^2} \exp\left(-\frac{\xi}{2t}\right)$$

Regularity solution Kolmogorov PIDE

Regularity of the solution of the Kolmogorov PIDE

Advantages

- ► If $\mathcal{L}^{(t,x)}C_{\text{pol}}^{\infty} \subseteq C_{\text{pol}}^{\infty}$ all the derivatives with respect of *s* exists.
- In the diffusive case regularity of (s, y) → v^(t,x)(s, y) has been proved already in [Talay and Tubaro, 1990].
- ► The Lévy case has been studied in [Jacod et al., 2005] and [Protter and Talay, 1997].

Regularity solution Kolmogorov PIDE

A one dimensional example: The Feller diffusion



 In [Alfonsi, 2005] regularity is obtained by using explicit expression of the density Regularity for Kolmgorov's equation driven by operators of Lévy type

Idea Use results in [Jacod et al., 2005] for Lévy driven SDE.

$$v^{(t,x)}(s,y) := \mathbb{E}^{y} \Big[f(L_{(1-s)}^{(T-t,x)}) \Big]$$

Sufficient conditions (Corollary 5.2. in [Protter and Talay, 1997])

▶ $f \in C_{\text{pol}}^k$

•
$$\int_{|\xi|\geq 1} |\xi|^k \nu(t,x,d\xi) < \infty$$

Then there exists a constant (depending on t and f) such that for all α multi-index with $|\alpha| \leq k$ there exists $M \in \mathbb{N}$ such that

$$|\partial_{(s,y)}^{\alpha}v^{(t,x)}(s,y)| \leq K(1+|y|^{\mathcal{M}}).$$

Back to the Feller diffusion: $dX_t^{\times} = 2\sqrt{X_t}dW_t$

Theorem (see Proposition 4.1. in [Alfonsi, 2005]) Given $f \in C_{pol}^k$, $\partial_x^{\alpha} u(t, x)$ is well defined and in C_{pol}^k for all $\alpha \in \mathbb{N}$. Moreover it is a classical solution of the PDE

$$\partial_t u(t, x) + 2x \partial_x^2 u(t, x) = 0,$$

 $u(T, x) = f(x).$

Proof:

For all
$$m \ge 0 \mathbb{E}^{x} \left[(X_t)^m \right] = \mathbb{E} \left[(L_x^t)^m \right] < \infty.$$

 $\stackrel{\leftarrow}{\rightarrow} \text{ for all } l \ge 0 \ \partial_s^l v(s, y) \text{ is smooth and of polynomial growth} \\ \stackrel{\leftarrow}{\rightarrow} \text{ for all } l \ge 0 \ \partial_x^k u(x, t) \text{ is smooth and of polynomial growth}$



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Conclusions and future research

- 1. The understanding of linear processes as path valued Lévy processes leads to numerical schemes based on the approximation of **'easy to simulate'** processes.
- 2. **Higher order schemes** can be derived by performing a Strang splitting instead of the Lie-Trotter splitting.
- 3. This perspective allows us to consider **path dependent options** written on a stock driven by an Affine process as a European style option written on a path valued process.

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References

Thank you

Lévy Khintchine decomposition of $\langle x, \Psi(t, u) \rangle$

For
$$i = 1, ..., m$$

 $\Psi_i(t, u) = \langle \mathbf{b}_i(t), u \rangle + \frac{1}{2} \langle \pi_J u, \sigma_i(t) \pi_J u \rangle - \mathbf{c}_i(t)$
 $+ \int_{D \setminus \{0\}} \left(e^{\langle u, \xi \rangle} - 1 - \langle \pi_J u, \pi_J h(\xi) \rangle \right) \nu_i(t, d\xi)$

For j = m + 1, ..., d

$$\Psi_j(t, u) = \left\langle \mathsf{b}_j(t), u \right\rangle.$$

Lévy Khintchine decomposition of $\langle x, \mathbf{R}(u) \rangle$

For
$$i = 1, ..., m$$

$$\mathbf{R}_{i}(u) = \langle \beta_{i}, u \rangle + \frac{1}{2} \langle \pi_{J} u, \alpha_{J}^{i} \pi_{J} u \rangle + \frac{1}{2} \alpha_{i,i}^{2} u_{i}^{2} - \gamma_{i}$$

$$+ \int_{D \setminus \{0\}} \left(e^{\langle u, \xi \rangle} - 1 - \langle \pi_{J \cup \{i\}} u, \pi_{J \cup \{i\}} h(\xi) \rangle \right) \nu_{i}(t, d\xi)$$

For
$$j = m + 1, ..., d$$

$$\mathbf{R}_j(u) = \langle \beta_j, u \rangle.$$



Construction

step1: Define the family of Markov kernels $(\wp_s(x, \cdot))_{s>0}$ $\wp_s(x, A) : (D_\Delta, \mathcal{B}(D_\Delta)) \to (\mathcal{D}(\mathbb{R}_{>0}; D_\Delta), \mathcal{F}),$ by $\wp_s(x, A) := \mathbb{P}^{sx}(A), A \in \mathcal{F}$ it is a convolution semigroup: $\wp_{s+t}(x,\cdot) = \mathbb{P}^{(s+t)x} = \mathbb{P}^{sx} * \mathbb{P}^{tx} =$ $\wp_{s}(X,\cdot) * \wp_{t}(X,\cdot).$ $\triangleright \omega_1 = \mathbb{P}^X$. step2: $\mathcal{D}(\mathbb{R}_{>0}; D_{\Delta})^{[0,1]} := \{ \varpi : [0,1] \to \mathcal{D}(\mathbb{R}_{>0}; D_{\Delta}) \}.$ step3: for any fixed $x \in D$, define the map $L_{sx}: \mathcal{D}(\mathbb{R}_{>0}; D_{\Lambda})^{[0,1]} \rightarrow \mathcal{D}(\mathbb{R}_{>0}; D_{\Lambda})$ $\varpi \mapsto \varpi_{s}$.

step4: $(\mathcal{G}_s)_{s \in [0,1]}$ the natural filtration generated by L.

Kolmogorov's existence Theorem

There exists a probability measure P on $(\mathcal{D}(\mathbb{R}_{\geq 0}; D_{\Delta})^{[0,1]}, \bigvee_{s \in [0,1]} \mathcal{G}_s)$ such that, for fixed $x \in D_{\Delta}$

$$P(L_{s_1x} \in d\omega_1, \ldots, L_{s_nx} \in d\omega_n) = \bigotimes_{k=1}^n \wp_{s_k-s_{k-1}}(x, d\omega_k - \omega_{k-1}),$$

with $0 = s_0 \le s_1 \le ... \le s_n \le 1$.

- $(L_{sx})_{s \in [0,1]}$ a stochastic process taking values in $\mathcal{D}(\mathbb{R}_{\geq 0}; D_{\Delta})$ with stationary and independent increments,
- In distribution L_{1x} coincide with X^x .
- It is stochastically continuous, i.e. lim_{s→t} ℘_s(x, ·) = ℘_t(x, ·) weakly on D(ℝ_{>0}; D_Δ) for every t ≥ 0 and x ∈ D.

Back to main.

For an affine process on $\mathbb{R}^m_{\geq 0}\times \mathbb{R}^n$ we can specify a set of admissible parameters

 $(b,\beta,a,\alpha,c,\gamma,m,M).$

with

•
$$b, \beta_i \in \mathbb{R}^d, i = 1, \ldots, d$$
,

• $a, \alpha_i, i = 1, \dots, d$ semi-definite positive matrices,

►
$$c, \gamma_i \in \mathbb{R}_{>0}, i = 1, \ldots, d,$$

• $m, M_i, i = 1, \ldots, d$ Lévy measures,

where d = n + m.

This set of parameters is called *admissible* for $D = \mathbb{R}^m_{>0} \times \mathbb{R}^n$ if

diffusion
$$a_{k,h} = 0$$
for $k \in I$ or $h \in J$, $\alpha_j = 0$ for all $j \in J$, $(\alpha_i)_{k,h} = 0$ if $k \in I \setminus \{i\}$ or $h \in I \setminus \{i\}$,

This set of parameters is called *admissible* for $D = \mathbb{R}^m_{>0} \times \mathbb{R}^n$ if

drift	
$b \in D$,	
$(\beta_i)_k \geq 0$	for all $i \in I$ and $k \in I \setminus \{i\}$,
$(\beta_j)_k = 0$	for all $j \in J$, $k \in I$

This set of parameters is called *admissible* for $D = \mathbb{R}^m_{>0} \times \mathbb{R}^n$ if

killing	
$\gamma_j = 0$	for all $j \in J$,
jumps	
supp $m \subseteq D$	and $\int_{D\setminus\{0\}} \left((x_I + x_J ^2) \wedge 1 \right) m(dx) < \infty$,
$M_j = 0$	for all $j \in J$,
$supp M_i \subseteq D$	for all $i \in I$ and
	$\int_{d \setminus \{0\}} \left((\pi_{l \setminus \{i\}}(x) + \pi_{J \cup \{i\}}(x) ^2) \wedge 1 \right) M_i(dx) < \infty$
	for all $i \in I$



Heston Model

$$dX_t^x = \sqrt{X_t^x} dB_t, \quad dY_t^y = -\frac{X_t^x}{2} dt + \sqrt{X_t^x} dW_t$$
$$R_1^H(u_1, u_2) = \frac{1}{2} \left(u_1^2 + u_2^2 - u_2 \right), \quad R_2^H(u_1, u_2) = 0$$

Idea: Solve the homogenous problem and then apply **nonlinear** variation of constants.

$$\Psi_1^H(t, u_1, u_2) = \underbrace{u_1 + \int_0^t R^C(\Psi_1^H(s, u_1, u_2))ds + tR_1^H(0, u_2)}_{\text{homogeneus part}}$$
$$= \Psi^C(t, u_1) + R_1^H(0, u_2) \underbrace{\int_0^t \partial_v \Psi^C(t - s, \Psi(s, u_1, u_2))ds}_{\text{Approximate by quadrature}}$$

The connection

Higher order approximation of the integral term coincides with higher approximation of the process.

Due to the representation of the Heston model as a time changed Brownian motion, one has $\mathbb{E}^{(x,0)}\left[e^{\langle u,Y_t\rangle}\right] = e^{x\Psi_t\left(t,R_1^H(0,u)\right)},$ where $x\Psi_{I}$ is the logarithm of the Fourier-Laplace transform of -0.1 the process I. The picture shows some approximated paths of Y when the path integral process *I* is approximated by composite trapezoid rule.



