Regularity Results for Degenerate Kolmogorov Equation of Affine Type

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Introduction and motivations

Affine processes

Examples and definitions Two key properties

The Result

Regularity on C_{pol}^{∞} Sketch of the proof

Outline

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Set up

The state space: $D \subset \mathbb{R}^d$

The model: $X = (\Omega, (\mathcal{F}_t)_{t \ge 0}, (X_t)_{t \ge 0}, (\mathbb{P}^x)_{x \in D_\Delta})$ càdlàg, time homogeneous, *conservative* Markov process in D

 $p_t(x, A) = \mathbb{P}^x(X_t \in A), \qquad t \ge 0, \ x \in D, \ A \in \mathcal{B}(D).$

The problem: Compute

$$P_t f(x) := \mathbb{E}^x \Big[f(X_t) \Big],$$

 $t \ge 0, x \in D, f \in \mathcal{M}.$

Option Pricing

The problem:

given

- $(X_t)_{t \in [0,T]}$ stock process
- ${\cal H}$ payoff function, possibly depending on the whole path up to time ${\cal T}$

find $\mathbb{E}^{\times} \Big[H(X_t, t \in [0, T]) \Big].$

Approximation of trajectories by MC methods

step 1 Fix a uniform partition in
$$[0, T]$$

 $\{t_0 = 0, ..., t_k = kh, ..., t_N = T\}, \quad h = \frac{T}{N}.$
step 2 Find a piecewise constant approximating process
 $(\widehat{X}_{t_k})_{k=0,...,N}$ such that
 $- \widehat{X}_{t_0}^x = x,$
 $- \widehat{X}^x$ is a weak ν -order approximation of X^x .

Definition

For every $f \in C^{\infty}$ with compact support there exists a K > 0 such that

$$\left|\mathbb{E}^{\mathsf{X}}\left[f(X_{\mathcal{T}})\right] - \mathbb{E}\left[f(\widehat{X}_{t_{N}}^{\mathsf{X}})\right]\right| \leq \mathsf{K}h^{\nu}.$$

Example

Heston model

Suppose X = (V, Y) with

$$\begin{cases} V_t = v + bt + \beta \int_0^t V_s ds + \varsigma \int_0^t \sqrt{V_s} dB_s^1 \\ Y_t = y - \frac{1}{2} \int_0^t V_s ds + \int_0^t \sqrt{V_s} dB_s^2, \end{cases}$$

where

- β , $\varsigma \in \mathbb{R}$, $b \in \mathbb{R}_{>0}$,
- $B = (B^1, B^2)$ is a Brownian motion in \mathbb{R}^2 with correlation.

Approximation of the square root process

Exact simulation

- high computation time
- need the knowledge of the exact distribution
- Euler scheme
 - not well defined
- ▶ NV splitting schemes [Ninomiya and Victoir, 2008]
 - do not rely on the specific model
 - high order convergence scheme
 - convergence holds under restrictions on the parameters
- Alfonsi scheme [Alfonsi, 2010]
 - extension of the NV schemes without restriction on the parameters

Convergence of weak schemes (see [Alfonsi, 2010])

The space $C^{\infty}_{pol}(D)$

$$C^{\infty}_{pol}(D) = \Big\{ f \in C^{\infty}(D), \text{ for all } \alpha \in \mathbb{N}^d \exists C_{\alpha} > 0, \eta_{\alpha} \in \mathbb{N} \\ \text{ for all } x \in D \ |\partial^{\alpha} f(x)| \le C_{\alpha}(1+|x|^{\eta_{\alpha}}) \Big\}.$$

Given $f \in C_{\text{pol}}^{\infty}$ there exists K(x, T) > 0 such that

$$\mathbb{E}^{\mathsf{X}}\left[f(X_{\mathcal{T}})\right] - \mathbb{E}\left[f(\widehat{X}_{t_{N}}^{\mathsf{X}})\right] \leq \mathsf{K}(\mathsf{X},\mathcal{T})h^{\mathsf{P}}$$

if...

Moment condition

i) for all $h \in (0, h_0)$ and $\alpha \in \mathbb{N}$ there exists a constant C_{α} such that $\mathbb{E}\left[|\widehat{X}_h^x|^{\alpha}\right] \leq |x|^{\alpha}(1+C_{\alpha})h + C_{\alpha}h,$

Short time approximation

ii) for all $h \in (0, h_0)$ there exist two constants C, E > 0 such that

$$\left| \mathbb{E}^{\mathsf{X}} \left[f(X_h) \right] - \mathbb{E} \left[f(\widehat{X}_h^{\mathsf{X}}) \right] \right| \le C h^{\nu+1} (1+|x|^E),$$

Regularity of the Kolmogorov equation

iii) the function
$$u(t, x) := \mathbb{E}^{x} [f(X_{t})]$$
 is well defined for $(t, x) \in [0, T] \times \mathbb{R}_{\geq 0}$, is a smooth solution of $\partial_{t} u(t, x) = \mathcal{A}u(t, x)$ such that, for all $\alpha \in \mathbb{N}^{d+1}$ multi-index it holds

for all
$$(t,x) \in [0,T] imes \mathbb{R}_{\geq 0}$$
, $|\partial^{\alpha}_{(t,x)}u(t,x)| \leq K(1+|x|^{\eta})$,

where K and η are positive constants depending on the time horizon T and the order of derivative α .

Question: When is iii) satisfied?

[Talay and Tubaro, 1990] If
$$X_t = x + \int_0^t b(X_s) ds + \int_0^t \sigma(X_s) dB_s$$
, with $b, \sigma \in C_{\text{pol}}^\infty$.

[Alfonsi, 2005] For the CIR model.

[G. 2014] For affine processes

- Lévy processes
- The Heston model
- ► The Bates model

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Affine processes

Examples and definitions

Examples of affine processes 1

Lévy processes

$$Y_{t} = \mathbf{y} + \mathbf{\mu}t + \mathbf{\sigma}B_{t} + \int_{0}^{t} \int \xi \mathbf{1}_{\{|\xi| \le 1\}} (J^{Y}(d\xi, ds) - m(d\xi)ds) + \int_{0}^{t} \int \xi \mathbf{1}_{\{|\xi| > 1\}} J^{Y}(d\xi, ds)$$

where (μ, α, m) is a Lévy triplet in \mathbb{R}^n , with $\alpha = \sigma \sigma^{\top}$.

Affine processes

Examples and definitions

Examples of affine processes 1

Lévy processes

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where (μ, α, m) is a Lévy triplet in \mathbb{R}^n , with $\alpha = \sigma \sigma^{\top}$.

$$\mathbb{E}^{\mathbf{y}}\left[e^{\langle u,Y_t\rangle}\right] = e^{t\eta(u) + \langle y,u\rangle}, \qquad u \in \mathbb{R}^n.$$

Affine processes

Examples and definitions

Examples of affine processes 2

Heston model

$$\begin{cases} V_t = v + bt + \beta \int_0^t V_s ds + \varsigma \int_0^t \sqrt{V_s} dB_s^1 \\ Y_t = y - \frac{1}{2} \int_0^t V_s ds + \int_0^t \sqrt{V_s} dB_s^2, \end{cases}$$

where

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where

-
$$\beta, \varsigma \in \mathbb{R}, b \in \mathbb{R}_{\geq 0}$$
,
- $B = (B^1, B^2)$ is a Brownian motion in \mathbb{R}^2 with correlation.

$$\mathbb{E}^{(v,y)}\left[e^{u_1V_t+u_2Y_t}\right] = e^{\phi(t,u_1,u_2)+v\psi(t,u_1,u_2)+yu_2}, \quad (u_1,u_2) \in \mathbb{R}^2.$$

Affine processes

Examples and definitions

Examples of affine processes 3

Bates model

$$\begin{cases} V_t = v + bt + \beta \int_0^t V_s ds + \varsigma \int_0^t \sqrt{V_s} dB_s^1 \\ Y_t = y - \frac{1}{2} \int_0^t V_s ds + \int_0^t \sqrt{V_s} dB_s^2 + J_t, \end{cases}$$

where

- *J* is a compound Poisson process

Affine processes

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Bates model

$$\begin{cases} V_t = v + bt + \beta \int_0^t V_s ds + \varsigma \int_0^t \sqrt{V_s} dB_s^1 \\ Y_t = y - \frac{1}{2} \int_0^t V_s ds + \int_0^t \sqrt{V_s} dB_s^2 + J_t, \end{cases}$$

where

- J is a compound Poisson process

$$\mathbb{E}^{(v,y)}\left[e^{u_1V_t+u_2Y_t}\right] = e^{\phi(t,u_1,u_2)+v\psi(t,u_1,u_2)+yu_2}, \quad (u_1,u_2) \in i\mathbb{R}^2.$$

Affine processes

Examples and definitions

In the above examples:

- V stochastic variance process in $\mathbb{R}^m_{>0}$,
- Y (discounted) log-price process in \mathbb{R}^n ,

and

- X := (V, Y) is a time homogeneous Markov process in $D := \mathbb{R}^m_{\geq 0} \times \mathbb{R}^n$,
- ► there exist functions $\phi : \mathbb{R}_{\geq 0} \times \mathcal{U} \to \mathbb{C}$ and $\Psi : \mathbb{R}_{\geq 0} \times \mathcal{U} \to \mathbb{C}^d$ such that

$$\mathbb{E}^{(\mathbf{v},\mathbf{y})}\left[e^{\langle u_1,V_t\rangle+\langle u_2,Y_t\rangle}\right]=e^{\phi(t,u_1,u_2)+\langle \mathbf{v},\Psi(t,u_1,u_2)\rangle+\langle \mathbf{y},u_2\rangle},$$

for $u = (u_1, u_2) \in \mathcal{U}$, where $\mathcal{U} = i\mathbb{R}^{m+n}$.

-Affine processes

Examples and definitions

Let

$$(\Omega, (X_t)_{t\geq 0}, (\mathcal{F}_t)_{t\geq 0}, (p_t)_{t\geq 0}, (\mathbb{P}^{\scriptscriptstyle X})_{\scriptscriptstyle X\in D})$$

be a time homogeneous Markov process. The process X is said to be an affine process if it satisfies the following properties:

- ▶ for every $t \ge 0$ and $x \in D$, $\lim_{s\to t} p_s(x, \cdot) = p_t(x, \cdot)$ weakly,
- ► there exist functions $\phi : \mathbb{R}_{\geq 0} \times \mathcal{U} \to \mathbb{C}$ and $\Psi : \mathbb{R}_{\geq 0} \times \mathcal{U} \to \mathbb{C}^d$ such that

$$\mathbb{E}^{x}\left[e^{\langle u,X_{t}\rangle}\right] = \int_{D} e^{\langle u,\xi\rangle} p_{t}(x,d\xi) = e^{\phi(t,u) + \langle x,\Psi(t,u)\rangle},$$

for all $x \in D$ and $(t, u) \in \mathbb{R}_{\geq 0} \times \mathcal{U}$, where $\mathcal{U} = \mathbb{C}_{\leq 0}^m \times i\mathbb{R}^n$.

-Affine processes

└─ Two key properties

Assumption (A)

X is conservative.

• There exists a function $\Psi : \mathbb{R}_{>0} \times \mathcal{U} \to \mathbb{C}^d$ such that

$$\mathbb{E}^{\mathsf{x}}\left[e^{\langle u, \mathsf{X}_t\rangle}\right] = \int_D e^{\langle u, \xi\rangle} \rho_t(\mathsf{x}, d\xi) = e^{\langle \mathsf{x}, \Psi(t, u)\rangle}$$

for all $x \in D$ and $(t, u) \in \mathbb{R}_{\geq 0} \times \mathcal{U}$.

For all $y \in \mathbb{R}^d$ and $x \in D$,

$$\mathbb{E}^{x}\Big[e^{\langle y, X_{\mathcal{T}}\rangle}\Big] < \infty$$

for some fixed T > 0.

-Affine processes

└─ Two key properties

AP as polynomial processes

 \mathcal{P}_η vector space of polynomials up to degree $\eta \geq 0$

$$\mathcal{P}_{\eta} := \left\{ \mathbb{R}^d \ni x \mapsto \sum_{|k|=0}^{\eta} lpha_k x^k \mid lpha_k \in \mathbb{R}
ight\}$$

Theorem 2.14 in [Cuchiero et al., 2008]

Under the Assumption (A), X is a a polynomial process, i.e. for all $\eta \in \mathbb{N}$ and $f \in \mathcal{P}_{\eta}$

$$x \mapsto \mathbb{E}^{x} \Big[f(X_t) \Big] \in \mathcal{P}_{\eta}, \quad \text{for all } t \geq 0.$$

- -Affine processes
 - LTwo key properties

AP from the perspective of path-space valued LP

Proposition 4.1. in [G., Teichmann, 2014]

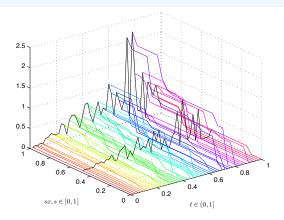
For each fixed t > 0 and $x \in D$, there exists a process $(L_s^{(t,x)})_{s \ge 0}$ such that:

- 1. $L_0^{(t,x)} = 0$,
- 2. for every $0 \le s_1 \le s_2 < \infty$, the increment $L_{s_2}^{(t,x)} L_{s_1}^{(t,x)}$ is independent of the family $(L_s^{(t,x)})_{s \in [0,s_1]}$ and it is distributed as $X_t^{(s_2-s_1)x}$,
- 3. it is stochastically continuous.

- -Affine processes
 - └─Two key properties

A different perspective

$$\mathbb{E}^{\mathsf{x}}\left[e^{u\mathsf{X}_{t}}\right] = e^{\mathsf{x}\frac{u}{1-2ut}} = \mathbb{E}\left[e^{u\mathsf{L}_{1}^{(t,\mathsf{x})}}\right]$$



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The Result

 \square Regularity on C_{pol}^{∞}

The result

Theorem [G., 2014]

Let $f \in C_{\text{pol}}^{\infty}$. Then, under the Assumption (A) the function $u : \mathbb{R}_{\geq 0} \times D \to \mathbb{R}$ defined by $u(t, x) = \mathbb{E}^{x} [f(X_{t})]$ is smooth, with all derivatives satisfying the following property:

for all $(t, x) \in [0, T] \times D$, $|\partial^{\alpha}_{(t,x)}u(t, x)| \leq K_{\alpha}(T)(1+|x|^{\eta_{\alpha}(T)})$,

where $K_{\alpha}(T)$ and $\eta_{\alpha}(T)$ are positive constants depending on the time horizon T and the order of derivative α .

The Result

Sketch of the proof

Dissect the theorem

part 1 $t \mapsto P_t f(x)$ is differentiable for all $x \in D$. \hookrightarrow Use iterated Dynkin formula.

part 2 $x \mapsto P_t f(x)$ is differentiable. \hookrightarrow Do a time-space shift.

part 3 $(t, x) \mapsto P_t f(x)$ is differentiable with controlled growth.

The Result

Sketch of the proof

Theorem: Regularity in time

Under the Assumption (A) it holds

(i) for any $f \in C^{\infty}_{\text{pol}}$, $P_t f$ solves the Kolmogorov's equation

$$\partial_t u(t, x) = \mathcal{A}u(t, x),$$

 $u(0, x) = f(x),$

for $(t, x) \in [0, T] \times D$,

(ii) for any $f \in C_{\text{pol}}^{\infty}$ and $\nu \in \mathbb{N}$ the following expansion of the transition semigroup holds for $(t, x) \in [0, T] \times D$:

$$\mathbb{E}^{x}\left[f(X_{t})\right] = f(x) + \sum_{k=1}^{\nu} \frac{t^{k}}{k!} \mathcal{A}^{k} f(x) + \mathcal{R}_{\nu} f(x, t),$$

where $\mathcal{R}_{\nu}f(x, t)$ is a remainder of order $\mathcal{O}(t^{\nu+1})$.

The Result

Sketch of the proof

Regularity in space

step 1 Consider the decomposition

$$X^{x+hx_i} \stackrel{law}{=} X^x + \widetilde{X}^{hx_i}, \ h > 0, \ i = 1, \dots, d,$$

where \widetilde{X}^{hx_i} is an independent copy of the process X starting from hx_i .

step 2 For fixed $(t, x) \in \mathbb{R}_{\geq 0} \times D$, $X_t^{x+hx_i}$ has the same distribution as the distribution of the Lévy process $L^{(t,x_i)}$ at time *h* starting from the initial random position X_t^x .

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Thank you